

## Ulisse Dini-type Helicoidal Surface in 3-Space

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### ABSTRACT

In this talk, we study Ulisse Dini-type helicoidal surface in Euclidean 3-space  $E^3$ . We give some basic notions of the three dimensional Euclidean geometry in section 2. In section 3, we consider Ulisse Dini helicoidal surface. We obtain Ulisse Dini-type helicoidal surface, and calculate its curvatures in the last section.

We calculate the first and second fundamental forms, matrix of the shape operator  $S$ , Gaussian curvature  $K$ , and the mean curvature  $H$  of surface  $M=M(u,v)$  in Euclidean 3-space  $E^3$ .

We define the rotational surface and helicoidal surface in  $E^3$ . For an open interval  $I \subset \mathbb{R}$ , let  $\gamma: I \rightarrow \Pi$  be a curve in a plane  $\Pi$  in  $E^3$ , and let  $\ell$  be a straight line in  $\Pi$ . A rotational surface in  $E^3$  is defined as a surface rotating a curve  $\gamma$  around a line  $\ell$  (these are called the profile curve and the axis, respectively). Suppose that when a profile curve  $\gamma$  rotates around the axis  $\ell$ , it simultaneously displaces parallel lines orthogonal to the axis  $\ell$ , so that the speed of displacement is proportional to the speed of rotation. Then the resulting surface is called the helicoidal surface with axis  $\ell$  and pitch  $a \in \mathbb{R} \setminus \{0\}$ . We may suppose that  $\ell$  is the line spanned by the vector  $(0,0,1)^t$ .

Moreover, we consider Dini-type helicoidal surface:

$$D(u,v) = \begin{pmatrix} \sin u \cos v \\ \sin u \sin v \\ \varphi(u) + av \end{pmatrix},$$

where  $\varphi(u): I \subset \mathbb{R} \rightarrow \mathbb{R}$  is a differentiable function for all  $u \in I \subset \mathbb{R} \setminus \{0\}$ ,  $0 \leq v \leq 2\pi$  and  $a \in \mathbb{R} \setminus \{0\}$ .

**Key Words:** Dini-type helicoidal surface, Gauss map, Gaussian curvature, mean curvature.

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